

Longitudinal Accelerating Vortex Described by Vector Equations using Open Vortex Theory

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ABSTRACT

The author considers an Accelerating longitudinal vortex with parameter $\varphi \approx 1.62$. This topic is developed in detail in the Theory of Open Vortices by the same author. It contains 2 Axioms and 8 Laws. In the present work, only 1 Axiom and 3 Laws are used. The Accelerating longitudinal vortex has unique properties. First, it sucks in transverse free Primary vortices in a direction perpendicular to the motion, generating nonlinearly arranged Accretion disks (from outside to inside). Second, it arranges and sucks in the free transverse Primary vortices in direction of motion, generating a suction Tunnel (from bottom to top).

The vector description shows that the Accelerating longitudinal vortex which has (n) number of turns, the angular velocity and radius decrease φ times, while the longitudinal velocity increases φ times with each turn. At the end, the Accelerating longitudinal vortex unravels and acquires only longitudinal velocity. All this is confirmed by Law 6 of the Theory of Open Vortices.

The Accelerating longitudinal vortices are attracted by suction and form an Accelerating Funnel. If the Accelerating Funnel includes (N) number of Accelerating longitudinal vortices, then the final acceleration increases (from the initial acceleration multiplied by φ to the power n) to the power (N).

Vector analysis shows that this acceleration becomes many times greater than the acceleration due to Gravity of Earth. All this is confirmed by applying Law 6. In the presence of positive acceleration, an initial acceleration and a certain type and volume of the fluid, Law6 calculates what weight such an Acceleration Funnel can lift up. But the independent operation of such an acceleration Funnel is unrealistic and cannot be executed. It is impossible to implement such successfully working Device.

That is why the author proposes a Device for successful generation an Accelerating longitudinal vortex which even increases efficiency increases the efficiency many times.

This Device includes an Accelerator, which is performed by a Volumetric Resonator in Space and Time. It is proved by Law 1 from Open Vortex Theory. According Law1, a Decelerating longitudinal vortex, wound transversely in plane, along a tube with a parameter φ , generates in the center of Gravity of the formed Volumetric Resonator inside the tube, an Accelerating longitudinal vortex in a direction perpendicular to the plane of the transverse tube.

Keywords: Longitudinal Vortex, Accelerating Vortex, Open Vortex Theory, Vector Equations, Vector Field Analysis, Vortex Dynamics, Fluid Dynamics.

Received: July 24, 2026;

Accepted: August 01, 2026;

Published: August 08, 2026

Open Vortex Theory

Axiom1: The movement of vector E with monotone-decreasing or monotone-increasing velocity (V) becomes along an Open vortex: $\text{div}(\text{Vor}E) \neq 0$: The new Axiom1 states that if velocity is uneven ($V \neq 0$) the vortex is Open. Thus, if there is an Open vortex, it is unevenly, or velocity is accelerating or decelerating (Figure 1b,c,e) [1,2]:

$\text{div}(\text{Vor}E) > 0$ -accelerating, $\text{div}(\text{Vor}E) < 0$ -decelerating.

Citation: Valentina Markova (2026) Hyper Speed by Decelerating Funnel based on Open Vortex Theory. J Modr Sci Scient Res 2: 1-8.

Law1: An open decelerating transverse vortex ($E_{2D}-$) inward in (2D) generates an open accelerating longitudinal vortex ($H_{3D}+$) outward in (3D). This action takes place from the Gravity center (G) of decelerating transverse vortex ($E_{2D}-$) by transverse-longitudinal operator for transformation ($\Delta 1-$), [2,3]:

$\Delta 1-$

Vor ($E_{2D}-$) => Vor ($H_{3D}+$)

Law 4: For an uneven (accelerating or decelerating) longitudinal vortex with current velocity (V_i) and current amplitude of the cross vortices (W_i), the product ($V_i \cdot W_i$) is a constant: **(V_i).(W_i) = const.,**

where $i = 0 \div \infty$ and the product ($V_i \cdot W_i$) is proportional with constant k to the Power of the uneven longitudinal vortex (P): **(V_i).(W_i) = $k \cdot P$**

Conservation Law claims that the complex action of velocity (V) and the amplitude of the transverse vortex (W) at a given moment (t_i) and at current point (p_i) is equal to the product: $V(t_i) \cdot W(t_i)$. It is a constant proportional to the Power of vortex.

- At a decelerating vortex vector **velocity** (V) is transformed according to internal law (by Golden proportion: $1/\varphi$) into the **amplitude** of the transverse vortex (W).
- At an accelerating vortex the amplitude of the cross vortex (W) is transformed according to internal law (by Golden proportion: φ) into a vector velocity (V).

Law 6: The acceleration vortex in 3D is described with 4 nonparametric equations in which: longitudinal velocity (V) increases in (n) portions (ψ^n) times, the angular velocity (ω), the amplitude (W) and the number (N_n) of Primary transverse vortices in a wheel, decrease to zero in (n) portions (ψ^n) times [3]:

$$V(t)^2 = V_0(V_0 + V(t)), W(t)^2 = W_0(W_0 - W(t)),$$

$$\omega(t)^2 = \omega_0(\omega_0 - \omega(t)), N^2 = N_0(N_0 - N_n),$$

where the roots v_n , w_n and N_n are expressed as: $v_n = (\psi^n)$. $V_0, \omega_n = (1/\psi^n)$, $\omega_0, w_n = (1/\psi^n)$. $W_0, N_n = (1/\psi^n)$. N_0 ; linear velocity V_0 is the starting value of V_n , amplitude of transverse vortex W_0 is the starting value of w_n , angular velocity ω_0 is starting value of ω_n , number N_0 is starting value of N_n ; ψ is a Golden proportion that fulfills the requirement: $\psi - 1/\psi = 1$; v_n, w_n and ω_n are periodic roots with period n ; v_n, w_n, ω_n are mutual orthogonal that fulfill the requirement for orthogonal: $v_n \cdot w_n = V_0 \cdot W_0$, $v_n \cdot \omega_n = V_0 \cdot \omega_0$; $n = 0 \div \infty$ [6];

Result: The Law6 describes a nonparametric process by Golden proportion ($1/\psi n$).

At an accelerating vortex vector velocity (+V) (first equation) is transformed into the amplitude of the transverse vortex (-W) (second equation). The increasing in speed (+ V_0) is transformed ($\psi n \cdot V_0$) into a decreasing in the amplitude (- W_0) of transverse vortices ($1/\psi n \cdot W_0$).

Results: The accelerating vortex suck in free primary cross vortices.

When an outer accelerating vortex passes through these Primary transverse vortices, according Law5 it will suck in them. As a result, the accelerating vortex will increase its positive acceleration, mass and Power. The reason is that it adds the mass

and Energy of the Primary vortices. An accelerating vortex with a velocity vector (+V) suck in Primary accelerating vortices with decreasing amplitude (-W) in perpendicular direction because of sign (-) in second equation. The sucking of accelerating transverse vortices from environment in perpendicular direction forms so called “quanta” and this process is called “quantum”.

Result: Accelerating vortex form decelerating right rotating wheels if see opposite to movement.

According to the Law1 the Primary accelerated transverse vortex generates (sucking) inward to it's a Primary longitudinal vortex (h) from the outside to inside. Thus, is formed at each point (i) a right rotating wheel. Because of the amplitude (-W), angular velocity (- ω) and the number of transverse vortices (-N) decreases it forms accelerating, stretching, narrowing, left rotating Funnel in which: only $V = \max$, but $W = \min$, $\omega = \min$, $N = \min$.

Result: The accelerating vortices form accelerating, stretching, narrowing, right rotating accelerating Funnel in which: $W_{\min}$, $\omega_{\min}$, $N_{\min}$.

At last, point the accelerating Funnel stops to rotate: $W=0$, $\omega=0$, $N=0$, but its longitudinal speed is maximal ($V_{\max}$).

Result: The final of accelerating Funnel does not rotate ($W=0$, $\omega=0$, $N=0$). It only moves straight with maximal speed ahead $V=\max$.

Due to the suction of Primary transverse vortices two or several accelerating vortices attract each other. They, insert one in another and form an accelerating Funnel.

Result: Two or several accelerating longitudinal vortices attract each other inserting one in another and form an accelerating Funnel.

In center inserts the fastest vortex, outside rotates vortex with less velocity and at periphery rotates vortex with the smallest speed. The reason for attraction is increasing the velocity with positive acceleration and decreasing the amplitude of Primary transverse vortices with positive acceleration as well.

Vector Calculation of a Longitudinal Accelerating Vortex with Parameter $\varphi \approx 1.62$

The mathematical model requires the definition of a coordinate system, since physical characteristics and operators are considered differently depending on the context.

Basic Vector Fields

The vector field of a vortex is determined by the rotation operator (curl), represented mathematically by the Hamiltonian vector operator (nabla):

$$\vec{\omega} = \nabla \times \vec{v}$$

where ($\omega^{\rightarrow}$) is the vector of the vortex (rotation), ($v^{\rightarrow}$) is the vector field of the longitudinal velocity.

a) Longitudinal Component

"Longitudinal" means that the vortex or its acceleration is directed in the direction of the main flow, the wave propagation vector or the central axis of symmetry. In cylindrical coordinates (r, θ , z) the axial component (along z) is sought:

$$(\nabla \times \vec{v})_z = \frac{1}{r} \left(\frac{\partial(rv_\theta)}{\partial r} - \frac{\partial v_r}{\partial \theta} \right)$$

b) Acceleration Component

If we consider an acceleration field ($\alpha^{\rightarrow}$), the longitudinal acceleration vortex (ξ) is expressed by the rotation of the acceleration:

$$\vec{\xi} = \nabla \times \vec{a}$$

c) Relationship with the Parameter $\phi \approx 1.62$.

The number ($\phi=1.618$) is known as the **Golden Ratio**. In the context of longitudinal vortices, it can refer to:

- **Spiral Trajectories:** The angle of vortex lines depends on Golden angle: ($d, d \cdot \phi, d \cdot \phi^2, d \cdot \phi^3 \dots 900$), which ensures **minimal resistance** to fluid motion.
- **Scaling Parameters:** In turbulent flows and nonlinear optics, the ratios between radial and longitudinal fields (transverse-longitudinal balance) can be optimized according to the Golden ratio [1-3].

A Specific Type of Accelerating Longitudinal Vortex with Parameter Φ , According the Theory of Open Vortices

a) Conservation Law

According Law4 of the Theory of Open Vortices, when the longitudinal velocity increases ϕ times, the angular velocity decreases ϕ times, describes the Law of Conservation of the kinematic constant in spiral-vortex flows, regulated by the Golden Section ($\phi \approx 1.62$) [2,3].

When the longitudinal velocity (v_z) increases ($\phi \approx 1.62$) times and the angular velocity (ω) decreases (ϕ) times, their product remains constant:

$$(v_z \cdot \omega = \text{const}) \cdot$$

This mathematically defines a **constant Power** of current points on this specific spiral.

b) Vector representation of this process:

According to Law 6 of the Theory of Open Vortices with a single parameter ϕ in 3D, when the longitudinal velocity increases ϕ times, the angular velocity, radius and number of primary vortices in each successive wheel N decrease ϕ times [2,3].

Longitudinal (axial) velocity:

$$v'_z = \phi \cdot v_z$$

Angular (rotational) velocity:

$$\omega' = \frac{\omega}{\phi}$$

Since the linear tangential velocity in the vortex is related to the angular velocity by the radius

$$v_\theta = \omega \cdot r$$

the new tangential velocity distribution becomes:

$$v'_\theta = \frac{v_\theta}{\phi}$$

c) Velocity vector field in cylindrical coordinates

In a cylindrical coordinate system (r, θ, z) the basic velocity vector field ($v^{\rightarrow}$) is written as:

$$\vec{v} = v_r \hat{e}_r + v_\theta \hat{e}_\theta + v_z \hat{e}_z$$

After applying the (ϕ) like a transformation rule, the new accelerated vector field ($v^{\rightarrow'}$) (assuming a stable radius ($v_r = 0$)) takes the form:

d) Calculating the Longitudinal Vortex (Rotation)

To find the axial (longitudinal) vortex, we apply the rotation operator (Ω') along the z-axis

$$(\nabla \times \vec{v}')$$

$$\vec{\Omega}'_z = (\nabla \times \vec{v}')_z = \frac{1}{r} \left(\frac{\partial(rv'_\theta)}{\partial r} - \frac{\partial v'_r}{\partial \theta} \right)$$

Substitute the transformed tangential velocity

$v'_\theta = v_\theta / \phi$, then:

$$\vec{\Omega}'_z = \frac{1}{r} \frac{\partial}{\partial r} \left(r \cdot \frac{v_\theta}{\phi} \right) = \frac{1}{\phi} \left[\frac{1}{r} \frac{\partial(rv_\theta)}{\partial r} \right] = \frac{1}{\phi} \vec{\Omega}_z$$

Result: At this specific acceleration, the local rotation of the longitudinal vortex itself decreases exactly (ϕ) times.

This means that in final step the Accelerating longitudinal vortex should stop rotates.

e) Dynamic acceleration and inertia force

If we calculate the total acceleration of the fluid element -the convective derivative:

$$((\vec{v} \cdot \nabla) \cdot \vec{v})$$

then the centripetal acceleration depends on the square of the tangential velocity:

$$a_r = - \frac{(v'_\theta)^2}{r} = - \frac{v_\theta^2}{\phi^2 \cdot r}$$

This shows that as the flow accelerates longitudinally (along the z-axis), the rotational pressure (centrifugal force) on the vortex walls decreases sharply by a factor ($\phi^2 \approx 2.62$). This is the principle of vortex **self-injection** and contraction observed in Victor Schauburger (by tubes and tornado structures), where energy is transferred from rotation to pure translation (Victor Schauburger 1885-1958) [4]. His mathematical model proves that with the relations:

$$v'_z = \phi v_z, \quad \omega' = \frac{\omega}{\phi}$$

Result: While the vector field retains its spatial Power, but the longitudinal vortex reduces its local rotation exactly ϕ times.

Conclusions: The conclusion that the current Power of the Accelerating longitudinal vortex remains constant is described in **Law 4** of the Open Vortex Theory of the present author.

The conclusion that the Accelerated longitudinal vortex decreases its local rotation expressed in angular velocity is described by **Law 6** of the Open Vortex Theory of the present author [1-3].

The Axis of the Spiral Is Straight but the Envelope Bends Like a Hyperbola

a) Hyperbolic Funnel

With this addition, the model acquires a fully completed physical and geometric meaning. It describes a hyperbolic Funnel vortex. In it, the center line (the axis) remains a perfectly straight line (the z-axis), but the outer envelope (the flow boundary) contracts and bends along a **hyperbola** with respect to the radius (R) and the height (z). The specific differential equation is written under these boundary conditions.

b) Geometric equation of the envelope:

The hyperbolic shape of the envelope means that the current radius of the Funnel of vortex (R) decreases inversely proportional to the height z along the straight axis. Since the geometry is bound by the parameter $\phi \approx 1.62$, the equation of the surface (C -the envelope) is defined as:

$$R(z) = \frac{C}{\phi \cdot z} \Rightarrow R(z) \cdot z = \text{const}$$

c) Differential Equation of Continuity (Mass Balance)

For an incompressible fluid, the mass conservation equation requires that the flow through each cross-section of the hyperbolic funnel be constant.

The cross-sectional area is: $A(z) = \pi \cdot R(z)^2$.

Since: $A(z) \approx 1/z^2$, to maintain the flow rate: $Q = A \cdot v_z$, the longitudinal velocity (v_z) must increase quadratically with z -depth:

$$\frac{\partial v_z}{\partial z} - \frac{2}{z} v_z = 0 \Rightarrow v_z(z) = v_{z0} \cdot z^2$$

d) Introducing the ϕ -kinematic condition

According to the basic Rule of Conservation and Law4 according Open Vortex Theory, when the longitudinal velocity increases ϕ times, the angular velocity decreases ϕ times:

$$v'_z = \phi v_z, \quad \omega' = \frac{\omega}{\phi}.$$

This means that the **local rate of change** along the z-axis is strictly fixed by ϕ . The differential equation that connects the two fields through the **spatial torsion** coefficient ($\ln \phi$) is:

$$\frac{1}{v_z} \frac{\partial v_z}{\partial z} = - \frac{1}{\omega} \frac{\partial \omega}{\partial z} = \ln \phi$$

Specific Differential Equation for the Longitudinal Vortex

a) Rotation (Ω_z)

To find the rotation (the vortex itself (Ω_z) inside the hyperbolic envelope, we use the tangential velocity ($v_\Omega = \omega \cdot r$). In cylindrical coordinates, the Navier-Stokes differential equation for this type of fluid torsion reduces to the relationship between the radial constriction of the hyperbola and the axial acceleration [5]:

$$v_z \frac{\partial \Omega_z}{\partial z} = (\ln \phi) \cdot \Omega_z \cdot v_z - 2\omega \left(\frac{\partial v_z}{\partial z} \right)$$

If we substitute the known values and rearrange, we obtain the pure differential equation of the vortex along the straight axis:

$$\frac{\partial \Omega_z}{\partial z} - (\ln 1.62) \Omega_z + \frac{4\omega_0}{z} = 0$$

b) Physical behavior of the accelerating longitudinal vortex with parameter $\phi(\approx 1.62)$

This differential equation describes the so-called **implosive vortex**. Since the envelope is a hyperbola, the fluid tends to the center (the straight axis). Since the longitudinal velocity increases rapidly (z^2), and the rotation decays ($1/z^2$), the vortex in its **final part stops rotating** as a macro-structure and turns into a **supersonic cumulative jet** with an extremely low pressure in the core, geometrically controlled by the Golden Ratio(ϕ).

In the Final Path, the Spiral Unravels as the Angular Velocity(ω) becomes Zero

a) Unraveling of the vortex

This is the logical and physical end of the process, known in hydrodynamics as complete lamination or **cumulative unraveling of the vortex**. When at the end of its path (at a critical length of the axis at final ($z = z_f$)) the angular velocity becomes exactly zero ($\omega = 0$), the **vortex structure ceases to exist** as a rotational motion. All the kinetic energy of the rotation is completely transformed into linear (translational) **kinetic energy along the straight axis**. Here is the specific mathematical and vector description of this final phase.

b) Boundary conditions for "untangling"

In order for the angular velocity to reach zero at the final point (z_f), the law of variation must go from asymptotic (exponential) to linear or power law with a finite root. Since the shell geometry is hyperbolic and the torsion parameter is ($\phi \approx 1.62$), the differential equation of the angular velocity in the final section takes the form:

$$\omega(z) = \omega_0 \left(1 - \frac{z}{z_f} \right)^\phi$$

At: $z = 0$, $\omega = \omega_0$ (maximum input rotation). At:

$$z = z_f, \quad \omega = \omega_0(0)^\phi = 0$$

Then complete untangling at the output.

Result: At Final Path of vortex, the rotation completes with untangling as $\omega_0(0)^\phi = 0$.

During this untangling the potential energy (E_p) of transverse rotation is completely transformed into kinetic energy (E_k) of longitudinal acceleration or: $E_p = 0$, $E_k = \text{max}$.

c) Differential equation of the Final Path

According Law6: v_z increases ϕ times when ω decreases ϕ times. Through this ratio specified the unwinding of the spiral is governed by the following differential system in the final zone:

$$\frac{dv_z}{dz} = \frac{\phi^2}{z_f - z} v_z$$

Substituting the differential for (ω), we obtain the equation for the final longitudinal acceleration:

d) Solution for the velocity and shape of the vortex

Integrating this differential equation gives us the exact profile of the longitudinal velocity at the **point of unraveling**:

$$v_z(z) = v_{z0} \cdot \left(1 - \frac{z}{z_f}\right)^{-\phi^2}$$

Since $\phi \approx 1.62$, then $\phi^2 \approx 2.62$. Due to the negative degree (-2.62), as (z) approaches z_f (z -final), the **denominator tends to zero**, which leads to a **mathematical singularity** (cumulative effect). The longitudinal velocity (v_z) is limited in practice only by the speed of light in the fluid or viscosity. The longitudinal velocity (v_z) **tends to infinity** and the angular velocity (ω) **tends to zero**:

$$v_z \rightarrow \infty \quad \omega \rightarrow 0.$$

The vector intensity of the longitudinal vortex is calculated by the rotation along the (z) axis. Since the tangential velocity is: $\mathbf{v}_\theta = \omega(\mathbf{z}) \cdot \mathbf{r}$, at the final point we have:

$$\vec{\Omega}_z = \frac{1}{r} \frac{\partial(rv_\theta)}{\partial r} = 2\omega(z)$$

At the final **moment of untangling** ($z = z_f$):

$$\vec{\Omega} = \vec{0}$$

Result: The velocity field is transformed from a spiral into a pure potential (vortex-free) field:

$$\vec{v} = v_z(z) \cdot \hat{e}_z$$

This means that the spiral is completely unwound and only the longitudinal velocity remains as hyper speed.

Physical Meaning of the Phenomenon

Dynamics

a) Implosion

This is the mathematical proof of the generation of a **hyper speed** linear jet by implosion. Instead of the fluid being dispersed centrifugally (explosion), the hyperbolic envelope and the parameter ϕ force the vortex to "wrap" so tightly around the straight axis that the spiral finally breaks (untwists). At this point, the rotational resistance disappears completely ($\omega=0$), the **friction with the walls drops to a minimum**, and the fluid is shot forward as a perfectly laminar, linear beam with colossal Kinetic Energy ($\mathbf{E}_k = \mathbf{max}$).

b) Acceleration on the Final Path of an Accelerating longitudinal vortex with parameter ϕ

The Accelerating longitudinal vortex (driven by the geometry of the Golden Section ($\phi \approx 1.62$)) is studied in non-standard aerodynamics as a **self-organizing process**. Here the acceleration

is not rectilinear as in Classical mechanics. The acceleration is following the logarithmic **Fibonacci spiral**.

When the vortex enters its Final Path (the focal point, the center of the narrowing Funnel or the so-called Confuser), the specific physical laws appear that determine the acceleration.

c) Mathematical expression of acceleration by ($\phi \approx 1.62$)

In an Accelerating longitudinal vortex that contracts according to the Golden ratio, the radius (r) **of the vortex decreases** by a factor (ϕ) with each rotation, and the **speed increases** proportionally by (ϕ).

Due to the **Law 4 (or Law of Conservation)** of angular momentum, the peripheral (final) velocity (v_f) is inversely proportional to the radius (r). Since the path is shortened, the final **centripetal** (radial) acceleration (a_r) at the end of the trajectory is calculated by the formula: $a_r = v^2/r$.

If in the final stage the radius (r_{fin}) has contracted (ϕ) times, and the final speed (v_{fin}) has increased (ϕ) times:

$$(r_{fin} = \frac{r_0}{1.62}) \quad | \quad (v_{fin} = 1.62 \cdot v_0)$$

Then the **final acceleration relative to the initial one** will be:

$$a_{fin} = \frac{(1.62 \cdot v_0)^2}{\frac{r_0}{1.62}} = 1.62^3 \cdot \frac{v_0^2}{r_0} \approx 4.25 \cdot a_0$$

This means that in the Final Path of the vortex the acceleration increases by more than 4 times (≈ 4.25) compared to the base value at the beginning of the vortex.

Result: In Final Path of vortex final acceleration increases more than 4 times:

$$a_{fin} > 4 \cdot a_0$$

Physics of the Final Path of the Vortex

For example, Final Path is described by Victor Schauburger in its tubes or vortex accelerator [4]. In nature and technology Final Path is described by the following dynamics:

a) Concentration of Kinetic Energy:

When the longitudinal vortex moves along its Final Path, the transverse (rotational) motion is converted into axial (longitudinal) at an **extremely high speed**.

b) Implosion instead of explosion:

The coefficient ($\phi \approx 1.62$) directs the motion inward towards the center. This creates a zone of strong rarefaction (**vacuum**) in the core of the vortex. It literally "sucks" and further accelerates the fluid (air or water). This is also proven by Law6 of Open Vortex Theory.

c) Reduction of resistance:

When the Golden ratio of ($\phi \approx 1.62$) is reached, the friction of the fluid on the walls of the vortex **tends to a minimum**, which allows the critical point to be passed **without loss of Energy**.

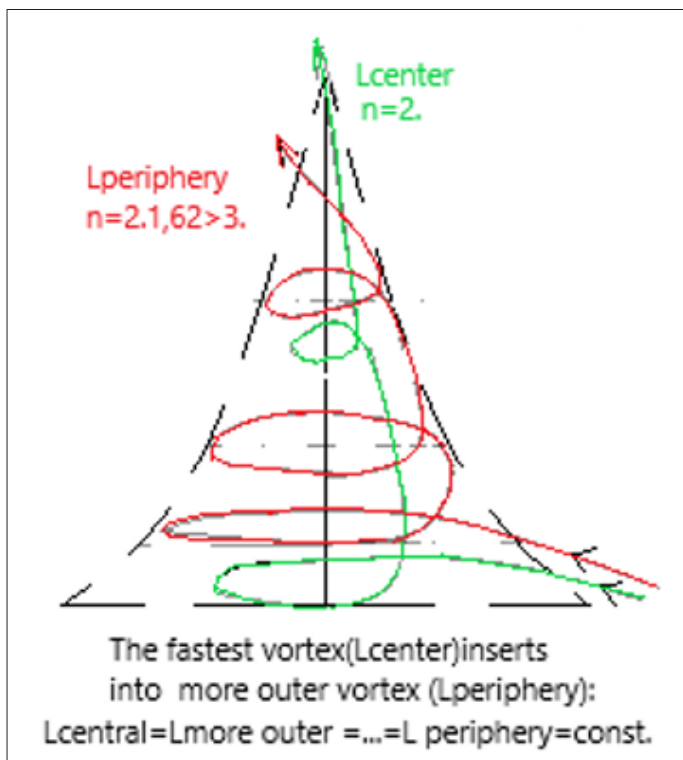


Figure 1: 3D Model of an Accelerating longitudinal vortex with $n_1=2$ turns.

An outer vortex with $n_2 = n_{1,\varphi} = 2$. $\varphi = 3,24 > 3$ turns. The length of spiral $L = \text{const}$.

d) An example for Accelerating Funnel with N=2 Accelerating vortices.

3D Model of an Accelerating longitudinal vortex with $n_1=2$ turns. An outer vortex with $n_2 = n_{1,\varphi} = 2$. $\varphi = 3,24$, $n_2 > 3$ turns. The length of spiral $L = \text{const}$. (Figure1).

e) An example for Accelerating Funnel with N=3 Accelerating vortices

Let we describe an Accelerating Funnel by N=3 number of Accelerating longitudinal vortices

- In central vortex $N=1$, $n_1=5$ turns.
- The second more outer Accelerating vortex should have $N=2$, $n_2 > n_{1,\varphi} = 5$. $1,62=8,10$, $n_2 > 8$ turns.
- The third Accelerating vortex should have $N=3$, $n_3 > n_{1,\varphi}^2 = 5$. $2,62=13,10$, $n_3 > 13$ turns.
- The length of spiral $L = \text{const}$. (Not Figure)

Mathematical Expression of the Acceleration At N= 5 Turns of Central Vortex of Accelerating Longitudinal Vortex by Parameter $\varphi \approx 1.62$

According Law6: in an Accelerating longitudinal vortex (which accelerates according to the Golden ratio φ) the radius (r) and the angular velocity decrease by a factor ($\varphi \approx 1.62$) with each rotation while the longitudinal velocity and positive acceleration increase (φ) times at each rotation.

a) If the initial acceleration a_0 is 1 m/sec²

So, if the initial acceleration a_0 is 1 m/sec², then the **final**

longitudinal acceleration (a_{zfin}) at the end of the first, second, third, fourth and fifth turns is calculated by the formula:

$$a_{z,1} = \varphi \cdot a_0 = 1.62 \cdot 1 \text{ m/sec}^2 = 1,62 \text{ m/sec}^2$$

$$a_{z,2} = \varphi^2 \cdot a_0 = 2.62 \cdot 1 \text{ m/sec}^2 = 2,62 \text{ m/sec}^2$$

$$a_{z,3} = \varphi^3 \cdot a_0 = 4,25 \cdot 1 \text{ m/sec}^2 = 4,25 \text{ m/sec}^2$$

$$a_{z,4} = \varphi^4 \cdot a_0 = 6,89 \cdot 1 \text{ m/sec}^2 = 6,89 \text{ m/sec}^2$$

$$a_{z,5} = \varphi^5 \cdot a_0 = 11.16 \cdot 1 \text{ m/sec}^2 = 11.16 \text{ m/sec}^2$$

If we have several n turns of the spiral, then the final acceleration (a_{fin}^n) will be equal to $a_{fin}^n = (1.62 \cdot a_0)^n$

Therefore, if the initial acceleration (a_0) is 1m/sec², then the final acceleration a_{fin}^5 with the number of turns $n=5$ will be equal to:

$$a_{fin}^5 = (1.62 \cdot a_0)^5 = 11.16 \text{ m/s}^2$$

Result: With an initial acceleration of 1m/sec² and 5 turns of the open accelerating longitudinal vortex, a final acceleration of more than 11.16 m/sec² is obtained

When we divide the final acceleration of 5 turns 11.16 m/s² by the acceleration due to gravity 9.8m/s² we get 1.13 times more

Result: The final acceleration (11.16 m/sec²) is 1.13 times greater than the acceleration due to Gravity of Earth (9.8 m/sec²).

This means that the final acceleration (11.16 m/sec²) is enough to launch a body into orbit around the Earth.

Mathematical Expression of the Acceleration in Accelerating Funnel of $n=3$ by Accelerating Longitudinal Vortices with $n=5$ Turns in the Central Vortex.

a) Let us generate an accelerating funnel with $N= 3$ accelerating longitudinal vortices inserted into each other (according to the magnitude of their speeds):

$$a_{Nfin} = (a_0 \cdot \varphi^n)^N = (1 \cdot \varphi^n)^N \text{ m/sec}^2.$$

-The fastest vortex is inserted into the center, to which we assign a minimum of $n_1 = 5$ turns, where r_1 is current radius. With an initial acceleration a_0 equal to 1m/sec² it has a longitudinal acceleration at the end:

$$a_{1fin} = (1 \cdot \varphi^{n_1})^3 \text{ m/sec}^2.$$

- It attracts the second, slower and more external vortex which will have $n_2 \approx 5 \cdot \varphi$ turns, r_2 is current radius, where $r_2 > r_1$ and $r_2 = r_1 \cdot \varphi^1$. Its own acceleration at the end is equal:

$$a_{2fin} = (1 \cdot \varphi^{n_2})^2 \text{ m/sec}^2$$

- The third peripheral and slowest vortex is wound from the outside, which will have $n_3 \approx 5 \cdot \varphi^2$ turns, where $r_3 = r_1 \cdot \varphi^2$ is current radius. Its own acceleration at the end: $a_{3fin} = (1 \cdot \varphi^{n_3})^1 \text{ m/sec}^2$

b) Diameters and number of turns in Funnel by 3 Accelerating longitudinal vortices

Geometric proportions of the three layers: If we take the basic current diameter of the central vortex at its starting point as (D_0), the three layers are arranged in a strict **fractal ratio** (Figure1):

Central vortex: Diameter = (D_0), Turns = **5**, while $L = \text{const}$.

Intermediate vortex: Diameter = $D_0 \cdot 1.62$, Turns = $5 \cdot 1.62 = 8.1$, while $L = \text{const}$.

Peripheral vortex: Diameter = $D_0 \cdot 1.62^2 = D_0 \cdot 2.6^2$, Turns = $5 \cdot 1.62^2 = 13.12$, while $L = \text{const}$.

c) "Spring (contract) Coiling"

Effect is a Constant Length (L). Since the length of Space is fixed (constant), the outermost vortices are forced to fit many more turns into the same distance along (z). This leads to a fundamental change in the kinematics:

Pitch compression at the periphery: The peripheral vortex has the **smallest pitch along (z)** (its coils are the most folded and dense). The flow there rotates intensively in the (x,y) plane, but moves more slowly forward along (z). It acts as a massive Energy reservoir - an "outer shell".

Pitch stretching in the center: The central vortex has only 5 turns for the same length (L). This means that its pitch is extremely elongated. The flow in it spends almost no time rotating in (x,y) but travels the distance along(z) with enormous linear velocity and powerful acceleration.

d) Results

Thus, with $n=5$ turns in the central vortex, and only $N=3$ number of accelerating longitudinal vortices, the final acceleration in the central vortex (A_{fin}) of the Funnel is maximum and will be:

$$A_{fin} = [a_{fin}^5]^3 = [(1,62 \cdot 1 \text{ m/cek})^5]^3 = [11,16 \text{ m/cek}^2]^3 > 1380 \text{ m/cek}^2$$

Result: The final acceleration (A_{fin}) in Accelerating Funnel is maximum and it is 1380 m/sec² (provided with 5 number turns in the Accelerating central vortex, and 3 number of Accelerating longitudinal vortices).

Result: The final acceleration (A_{fin}) in Accelerating Funnel is 141 times greater than the acceleration due to Gravity (9.8 m/sec²) (provided with 5 turns in the Accelerating central vortex, and 3 number of Accelerating longitudinal vortices).

e) The Reasons

Internal reason: The central internal vortex with its maximum final **Internal acceleration** sucks the Primary free the transverse vortices of the neighboring more outer vortex, which it sucks the transverse vortices of the peripheral vortex. In this way, the central internal vortex sucks mass of all the Primary free transverse vortices (from outward to inward) as well the Energy of the two outer vortices and amplifies its own acceleration.

External reason: In the center $n=5$ rings with decreasing radii are created in the direction of fluid movement which play the role of Accelerator. At the same time suck an additional **External acceleration** vortex in perpendicular direction (from down to up) in the direction of the main vortex. It is this external accelerated vortex sucked in perpendicular direction (down-up) is that further it additionally accelerates its own Internal acceleration vortex. This effect multiplies (3 times b) by using the Funnel of $N=3$ longitudinal accelerating vortices.

Result: The Internal acceleration vortex depends on Volume and the physical properties of the fluid.

The magnitude of an Internal acceleration depends on a_0 , n and N and also of Volume and of the physical properties of the fluid (viscosity, adhesion, cohesion etc.)

Result: The External acceleration vortex (from down to up) accelerates all structure of Accelerating Funnel. External acceleration tightens Funnel in radius and accelerates it further in z-axis.

Result: The External acceleration creates added mass and External Added Energy.

The External Added Energy is the result of the effect of resonance in Resonator. This is a resonance in Space and Time. Depending on the success of construction and design of Resonator, this resonance has a coefficient of useful action from zero to a maximum. Because the coefficient depends on construction, it is not possible to calculate exactly how large the effect is. But there is always an effect of Added Value of Energy.

Unique Non-parametric Resonance with Super Self-acceleration

Explanation

a) **Physics of the Final Path of the vortex according to Classical nonlinear vortex dynamics.**

In nature and technology (for example, in Victor Schauburger tubes or vortex accelerators) this process is described by the following dynamics [4].

Concentration of Kinetic Energy: When the longitudinal vortex moves along its final path, the transverse (rotational) motion is converted into axial (longitudinal) motion at an extremely high speed.

Implosion instead of explosion: The coefficient ($\varphi \approx 1.62$) directs the motion inward towards the center. This creates a zone of strong rarefaction (**vacuum**) in the vortex core, which literally "sucks" and further accelerates the fluid (air or water).

Reduction of resistance: When reaching the Golden ratio of 1.62, the friction of the fluid in the walls of the vortex **tends to a minimum**, which allows the passage of the critical point without loss of Energy.

b) **Physics of the Final path in turn the Theory of Open Vortices with a parameter φ .**

The dynamics of the accelerating longitudinal vortex is described by Law 6. It sucks in Primary vortices from the environment and they **add their speed and mass to the main** vortex with positive acceleration. Thus, the accelerating longitudinal vortex with an initial positive acceleration **is self-accelerating** [3,5,6].

According Law6: the longitudinal velocity (v) and acceleration increase φ times but the angular velocity (ω), number of transverse vortices in current wheel and radius (r) decrease φ times.

The necessary condition is that there is an initial positive acceleration (a_0) (a push).

The sufficient condition is that this push continues for several steps. At each step, the acceleration increases, and the angular velocity and radius decrease 1.62 times.

The reason for self-acceleration is that additional Energy is sucked in and added to its own Energy. This process proceeds in an avalanche-like manner with **Positive Feedback** until the value of the velocity and acceleration become saturated, and this

is repeated at the next saturation point. Generating acceleration **does not violate the Law of Conservation** because the suction of external free vortices continuously adds external Energy. This is precisely what causes the generation of acceleration.

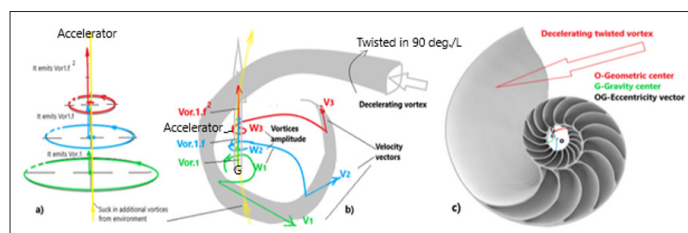


Figure 2: Algorithm of generating Accelerating longitudinal vortex: a) Accelerator by decreasing radius of open accelerating vortices, arranged one above other; b) Decelerating longitudinal vortex (twisted in 90degree to length of vortex L) generates in Gravity center(G) an Accelerating longitudinal vortex (Law1); c) An exemplary generator of a Super-Accelerating longitudinal vortex by means of a Decelerating twisted longitudinal vortex.

Comparison

- In mechanical pendulum resonance, the **resonance is parametric** and depends on external shocks. In order to continuously increase the amplitude. To accelerate the swing, the shocks from the outside, which are in phase with the maximum deviation, must be of increasing Force.
- In Electromagnetic resonance, the **resonance is also parametric** and depends on the magnitude of the external pulses.
- The resonance of the Accelerating longitudinal vortex is **non-parametric resonance**. The shocks with increasing **Force** by vortices in n turn (for example n=5) are internal (from bottom to top) with parameter φ : $(F_{1,\varphi}^0)$, $(F_{1,\varphi}^1)$, $(F_{1,\varphi}^2)$, $(F_{1,\varphi}^3)$, $(F_{1,\varphi}^4)$.

First: They represent suction Forces and they suck all Primary transverse vortices in **transverse direction** by an accelerating manner (Figure 2a).

Second: They create a channel (Tunnel) for additional Force of additional suction.

This suction is along **perpendicular direction** from the outside to inside through so called Tunnel of suction. The Tunnel sucks in and arranges the free Primary transverse vortices toward inside. Namely this additional suction generates this **super-acceleration** which need for us (Figure 2b).

Execution

An example of Generator of Accelerating longitudinal vortex and Funnell with super positive acceleration (Figure2c) [6-8].

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